

**ARCHITECTURAL STRUCTURES I:
STATICS AND STRENGTH OF MATERIALS**

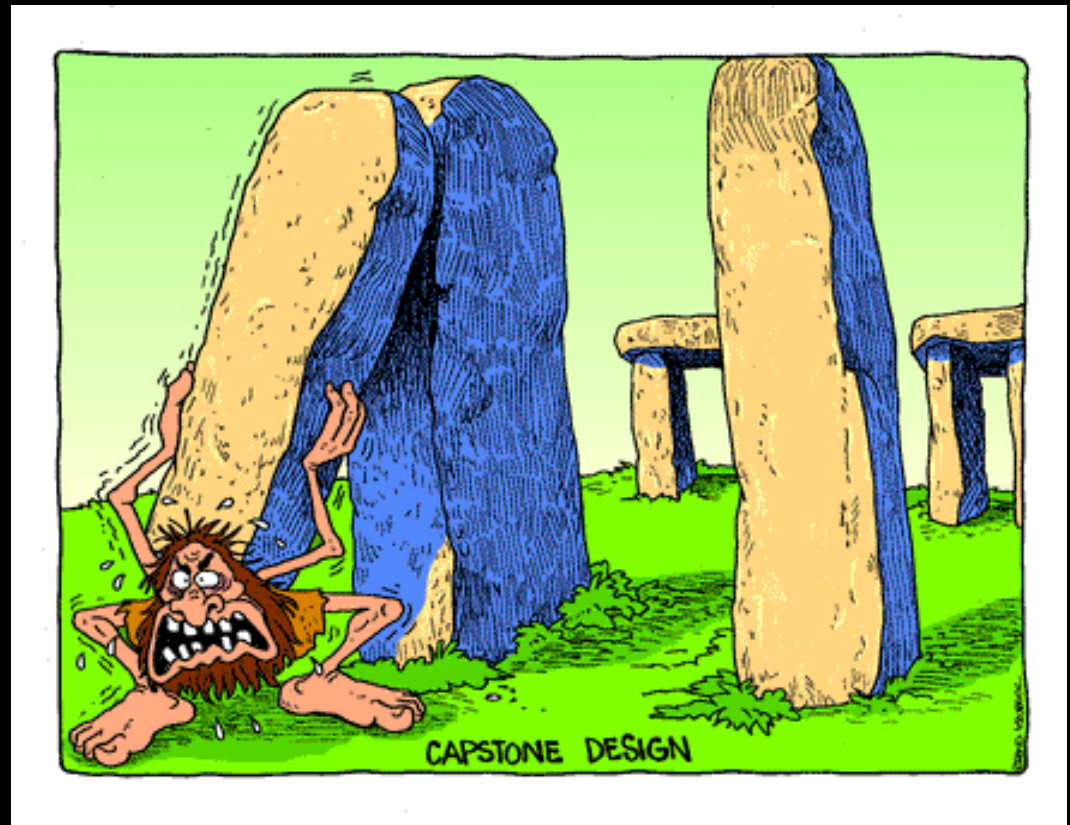
ENDS 231

DR. ANNE NICHOLS

SPRING 2008

**lecture
five**

**rigid body
equilibrium**



Equilibrium

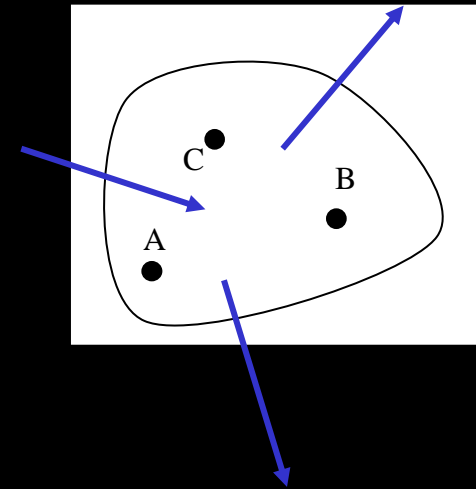
- *rigid body*
 - *doesn't deform*
 - *coplanar force systems*

- *static:*

$$R_x = \sum F_x = 0$$

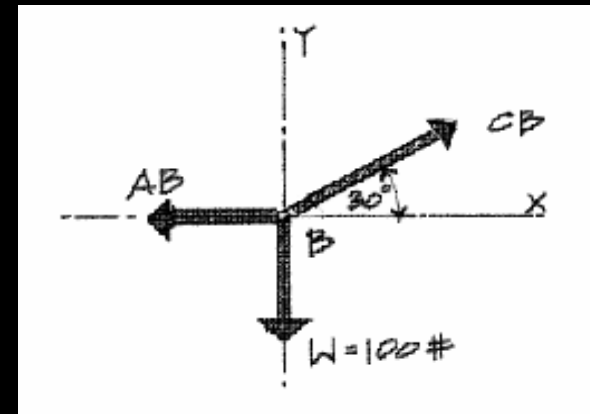
$$R_y = \sum F_y = 0$$

$$M = \sum M = 0$$



Free Body Diagram

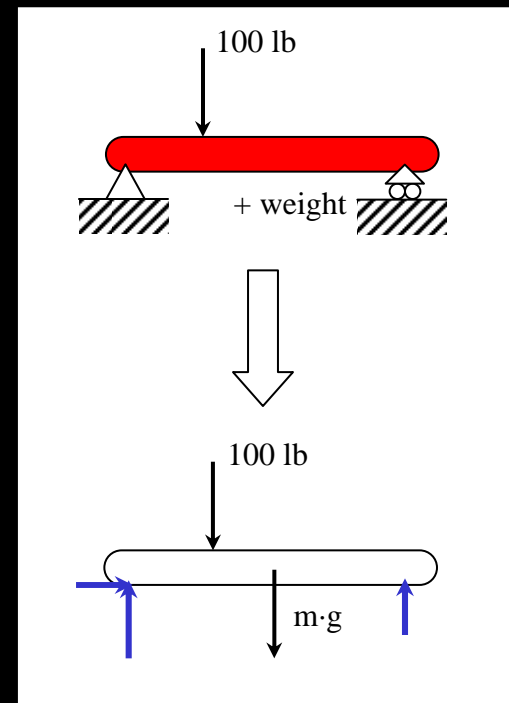
- *FBD (sketch)*
- *tool to see all forces on a body or a point including*
 - *external forces*
 - *weights*
 - *force reactions*
 - *external moments*
 - *moment reactions*
 - *internal forces*



(Example 1)

Free Body Diagram

- *determine body*
- *FREE it from:*
 - *ground*
 - *supports & connections*
- *draw all external forces acting ON the body*
 - *reactions*
 - *applied forces*
 - *gravity*

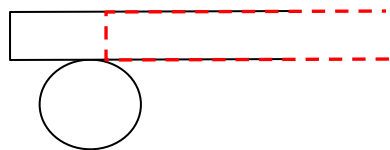


Free Body Diagram

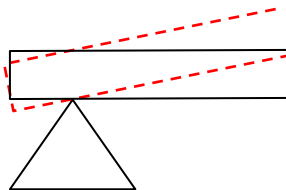
- *include relevant geometry*
 - *guidelines helpful to see moment arms*
- *name and/or color the unknown*
 - *forces*
 - *moments*
 - *angles*
- *solve up to 3 equations*

Reactions

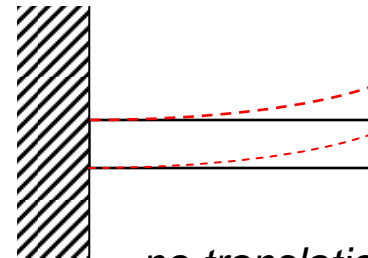
- *result of applying force*
- *unknown size*
- *connection or support type*
 - *known direction*
 - *related to motion prevented*



no vertical motion

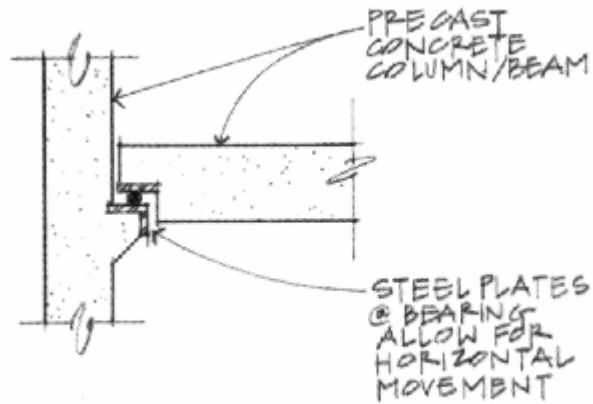


no translation

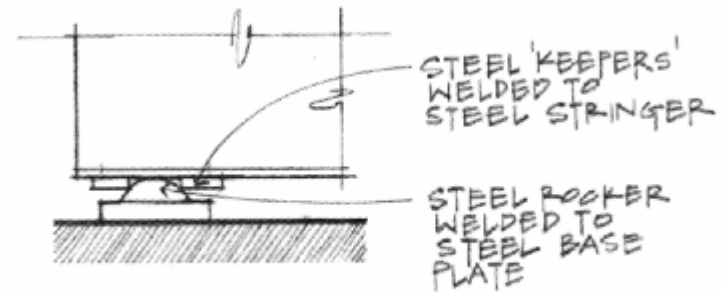


*no translation
no rotation*

Supports and Connections



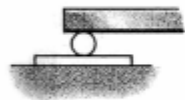
Roller



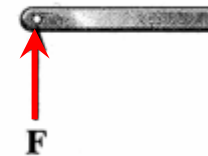
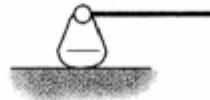
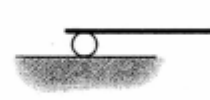
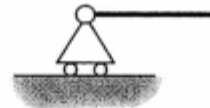
Rocker



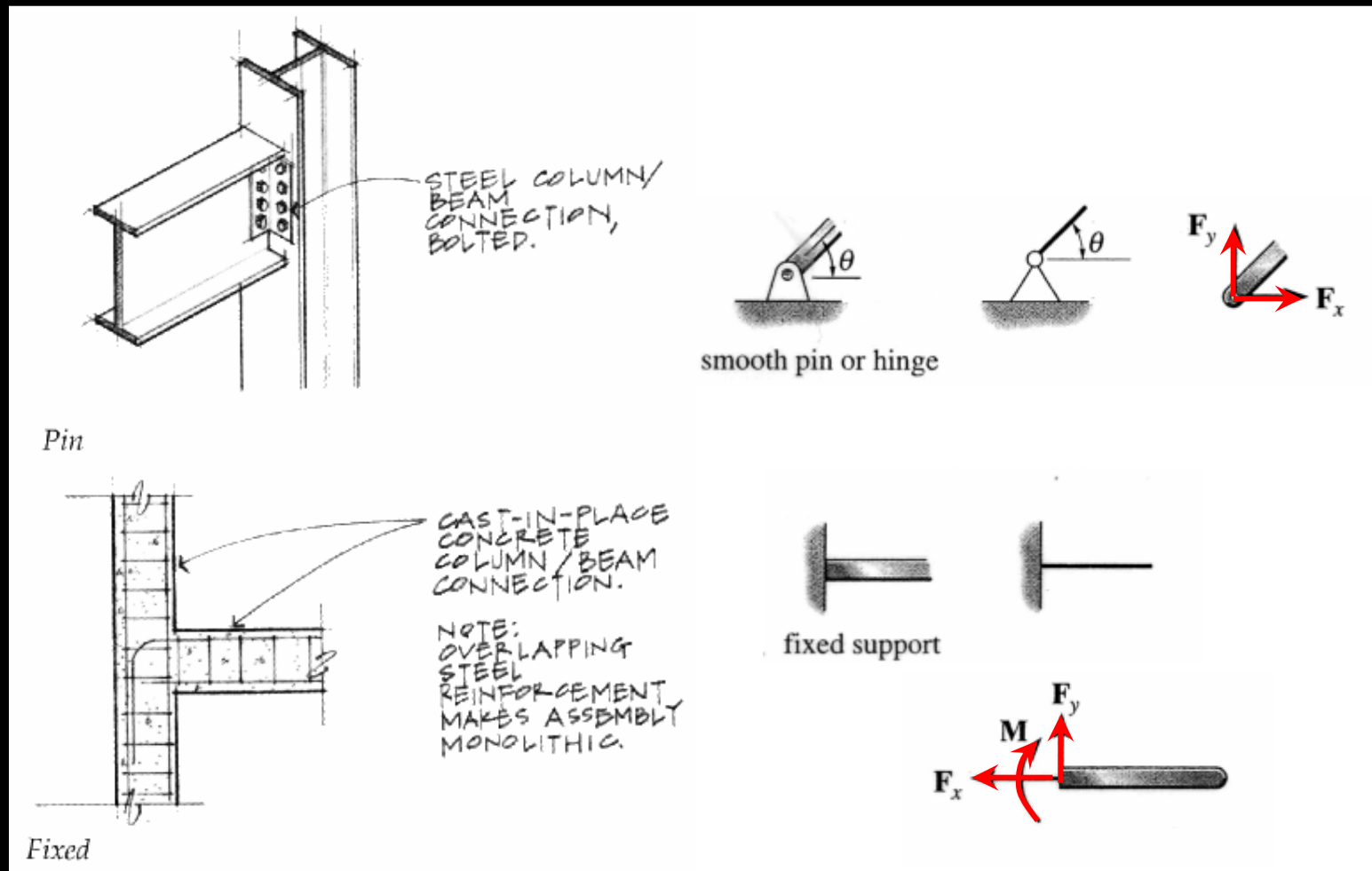
rollers



rocker

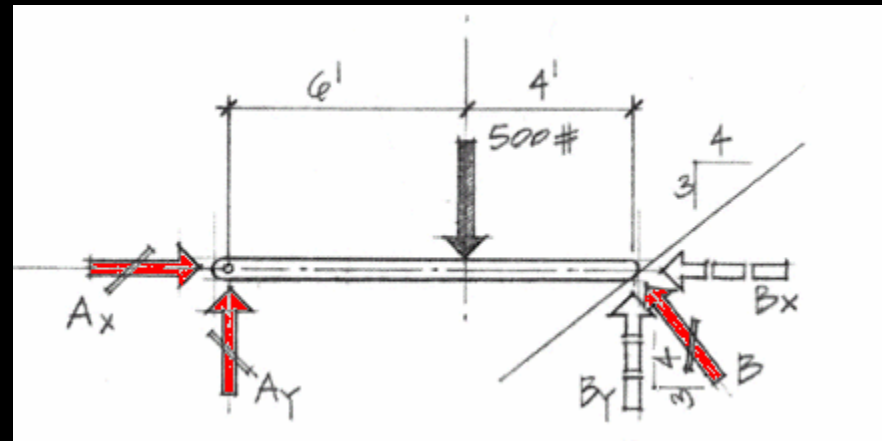
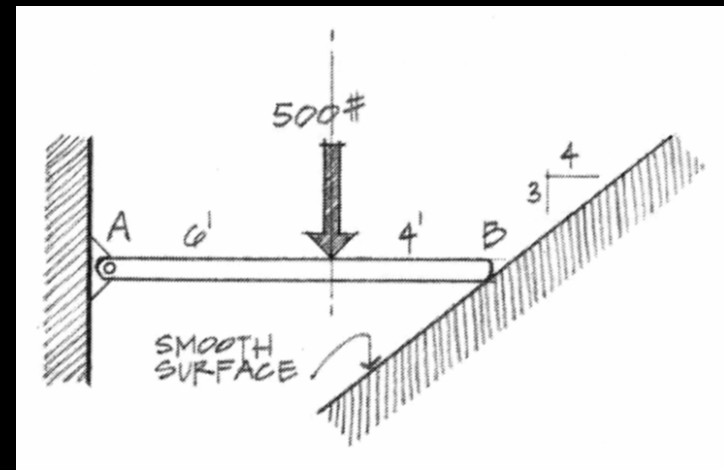


Supports and Connections



FBD Example

- 500 lb known
- pin – A_x , A_y
- smooth surface –
B at 4:3
- 3 equations
- sum moments at
 - A?
 - B? (B_x)



Moment Equations

- *sum moments at intersection where the most forces intersect*
- *multiple moment equations may not be useful*
- *combos:*

$$\sum F_x = 0$$

$$\sum F_y = 0$$

$$\sum M_1 = 0$$

$$\sum F = 0$$

$$\sum M_1 = 0$$

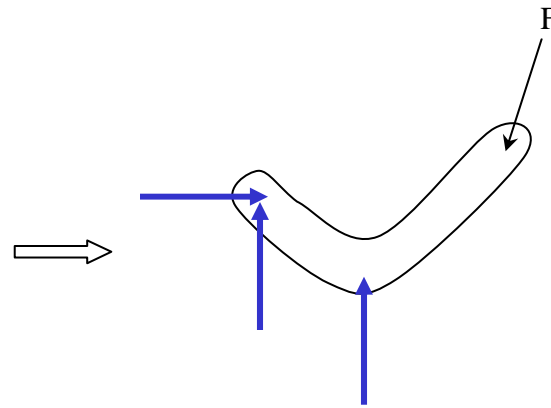
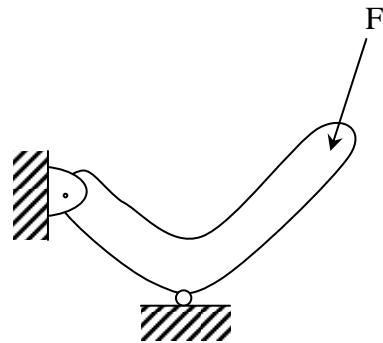
$$\sum M_2 = 0$$

$$\sum M_1 = 0$$

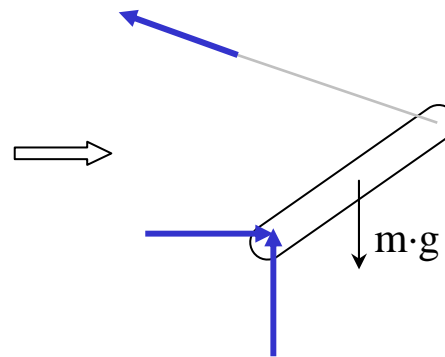
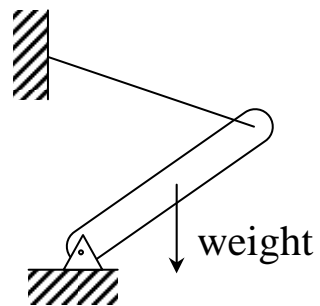
$$\sum M_2 = 0$$

$$\sum M_3 = 0$$

Recognizing Reactions

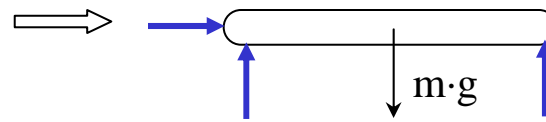
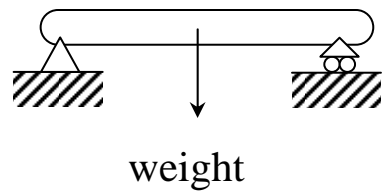


3
unknowns

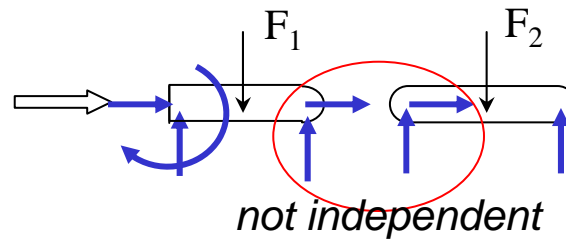
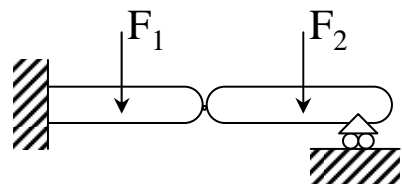


3
unknowns

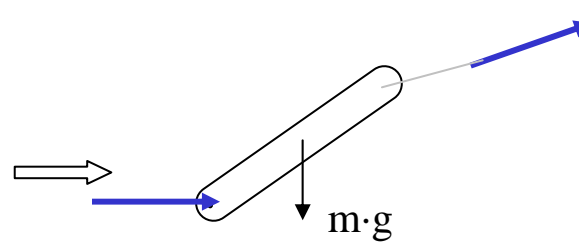
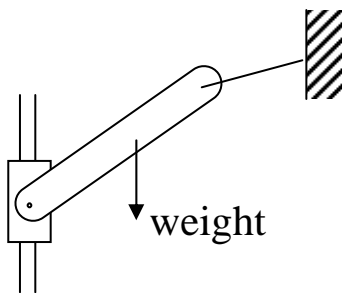
Recognizing Reactions



3
unknowns



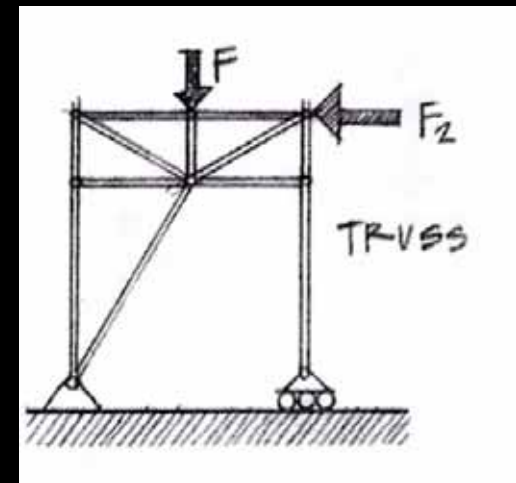
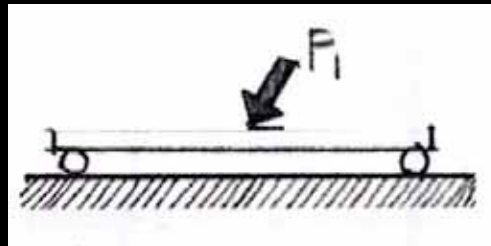
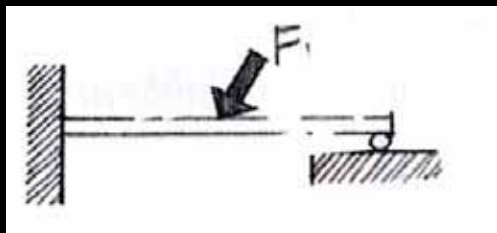
6
unknowns for
2 bodies



2
unknowns

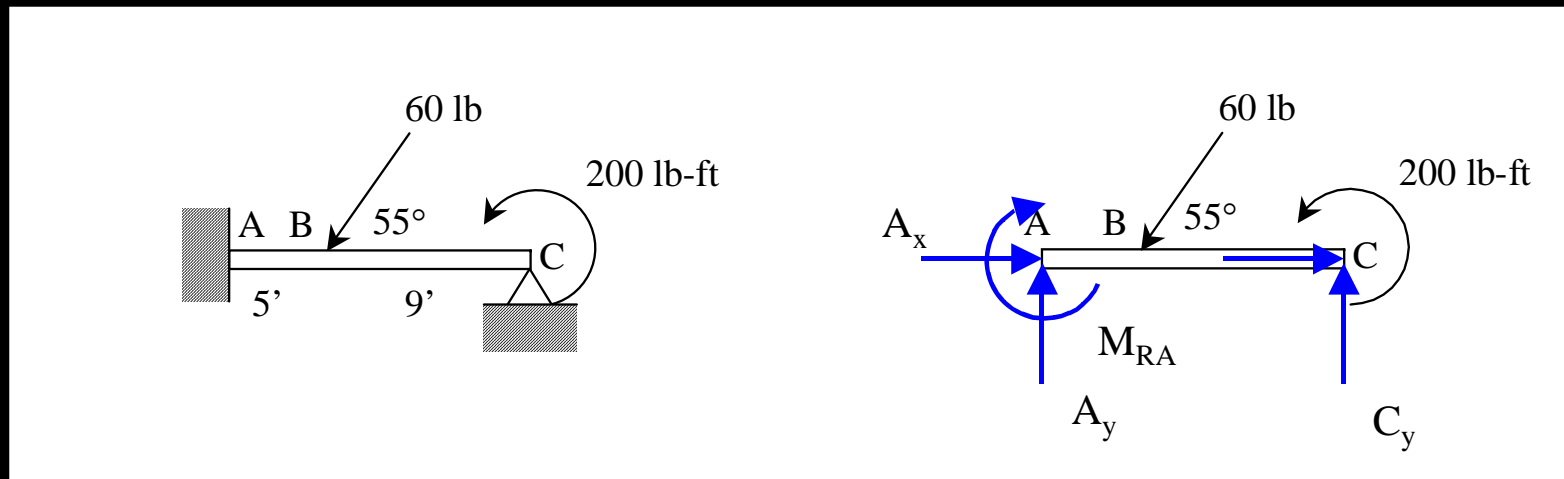
Constraints

- *completely constrained*
 - *doesn't move*
 - *may not be statically determinate*
- *improperly or partially constrained*
 - *has \leq unknowns*
 - *can't solve*

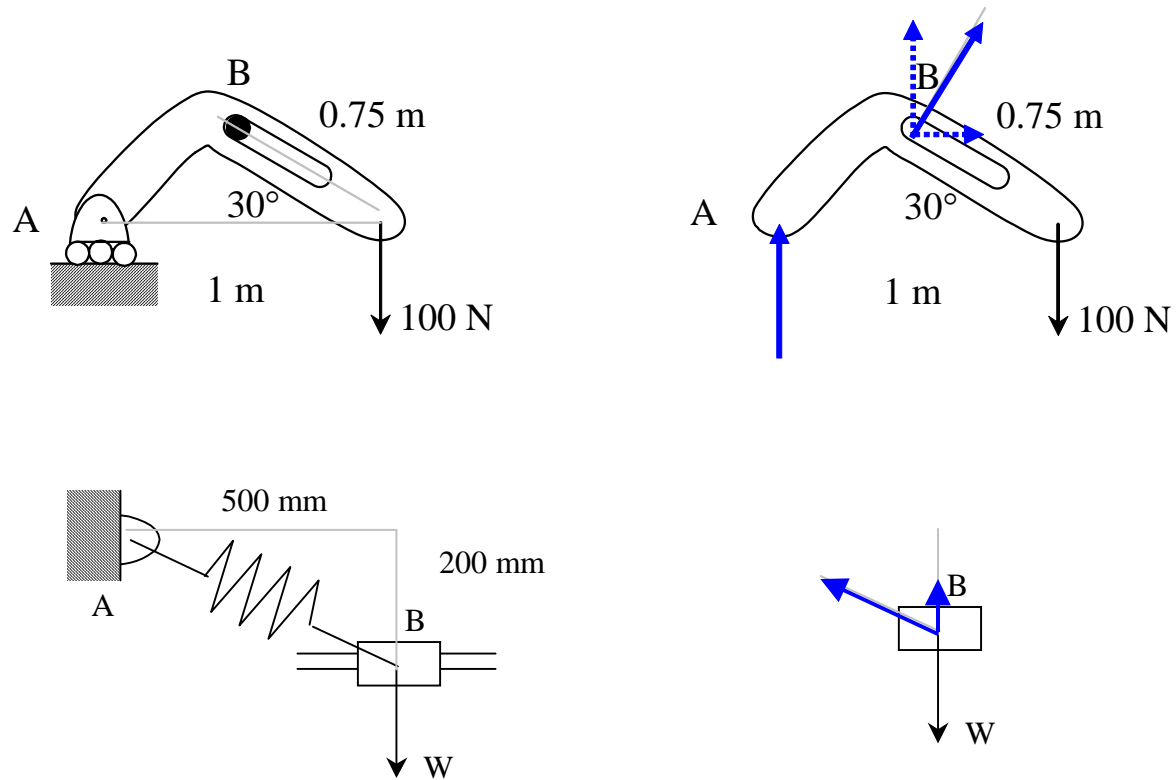


Constraints

- *overconstrained*
 - *won't move*
 - *can't be solved with statics*
 - *statically indeterminate to n^{th} degree*

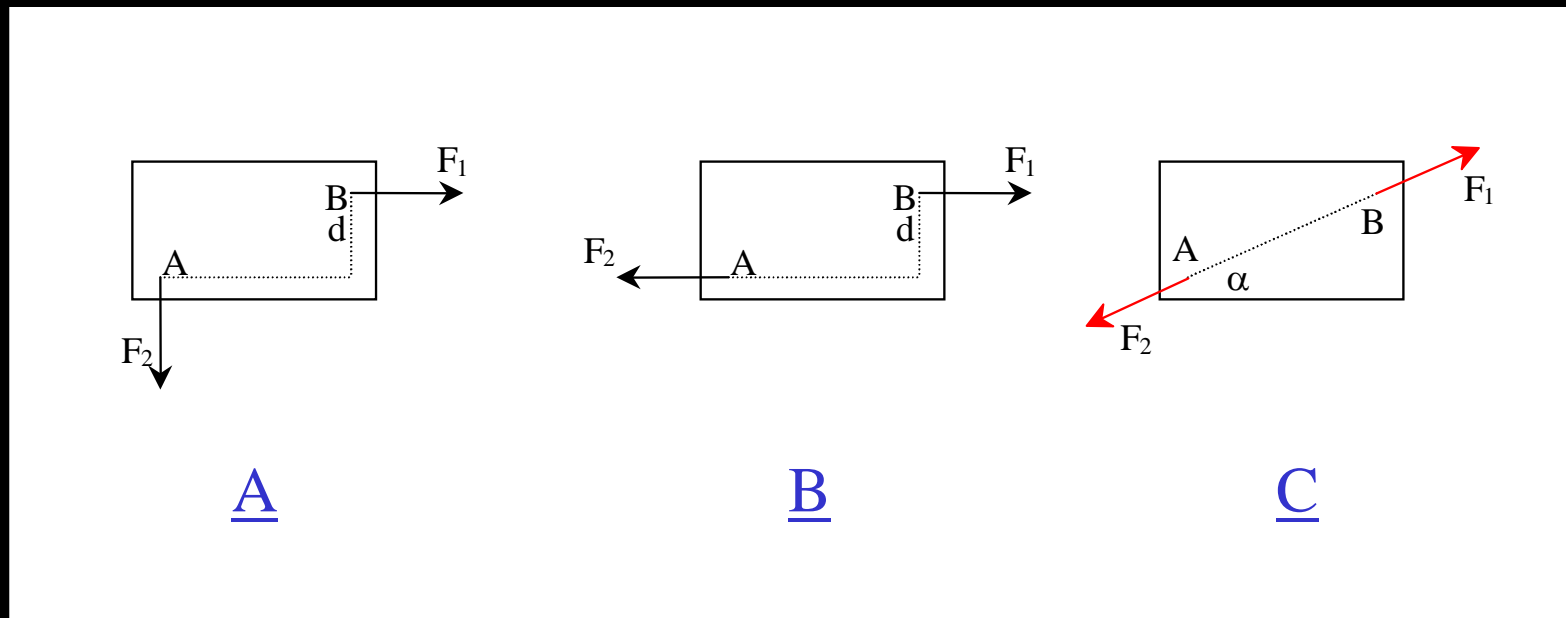


Partial Constraints



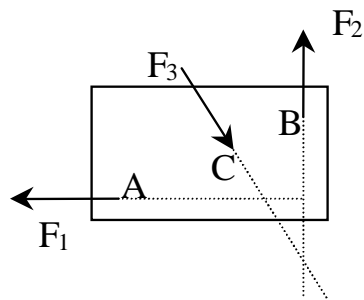
Two Force Rigid Bodies

- *equilibrium:*
 - forces in line, equal and opposite

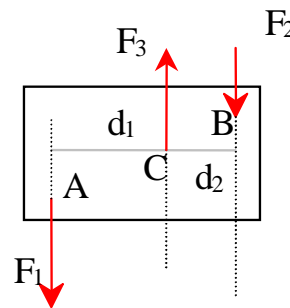


Three Force Rigid Bodies

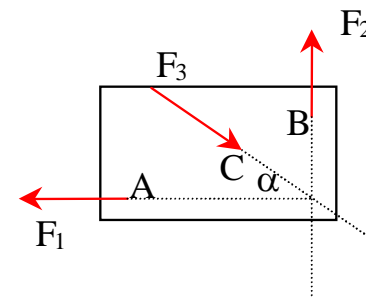
- *equilibrium:*
 - *concurrent or parallel forces*



A (no)



B



C

Cable Reactions

- *equilibrium:*
 - *more reactions (4) than equations*
 - *but, we have slope relationships*
 - *x component the same everywhere*

