ARCHITECTURAL STRUCTURES I:

STATICS AND STRENGTH OF MATERIALS

**ENDS 231** 

DR. ANNE NICHOLS
SUMMER 2006

lecture twelve



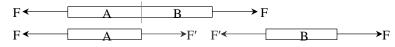
# beam forces – internal

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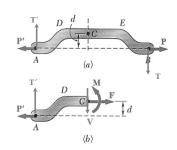
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#### Internal Forces

- trusses
  - axial only, (compression & tension)

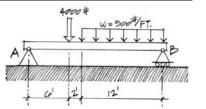


- in general
  - axial force
  - shear force, V
  - bending moment, M



#### **Beams**

- span horizontally
  - floors
  - bridges
  - roofs



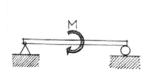
- loaded transversely by gravity loads
- may have internal axial force
- will have internal shear force
- will have internal moment (bending)

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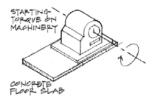
# Beam Loading

- concentrated force
- concentrated <u>moment</u>
  - spandrel beams





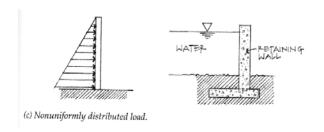
(d) Pure moment.



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#### Beam Loading

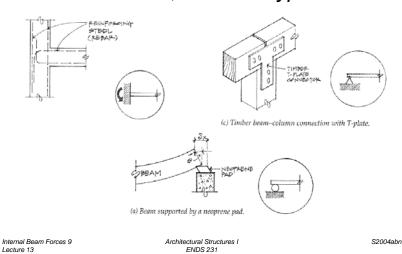
- uniformly distributed load (line load)
- non-uniformly distributed load
  - hydrostatic pressure
  - wind loads



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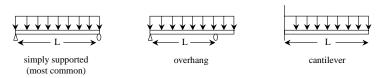
# Beam Supports

• in the real world, modeled type

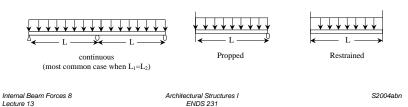


#### Beam Supports

statically determinate

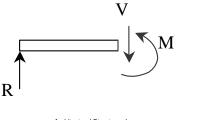


statically indeterminate



## Internal Forces in Beams

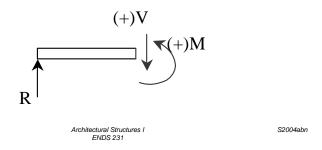
- like method of sections / joints
  - no axial forces
- section must be in equilibrium
- want to know where biggest internal forces and moments are for designing



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#### V & M Diagrams

- tool to locate V<sub>max</sub> and M<sub>max</sub>
- necessary for designing
- have a different sign convention than external forces, moments, and reactions

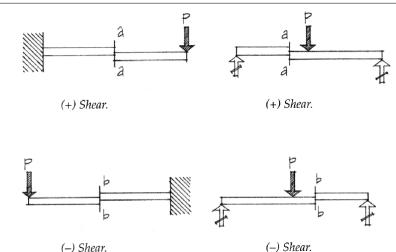


# Shear Sign Convention

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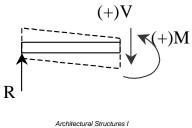


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### Sign Convention

- shear force, V:
  - cut section to LEFT
  - if  $\Sigma F_v$  is positive by statics, V acts down and is POSITIVE
  - beam has to resist shearing apart by V



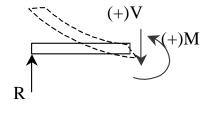
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# Sign Convention

- bending moment, M:
  - cut section to LEFT
  - if  $\sum M_{cut}$  is clockwise, M acts ccw and is POSITIVE - flexes into a "smiley" beam has to resist bending apart by M



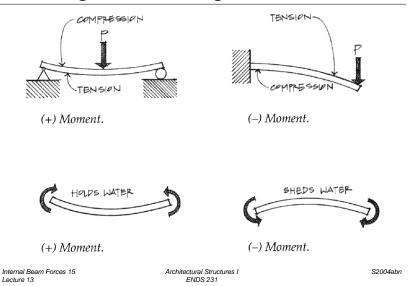
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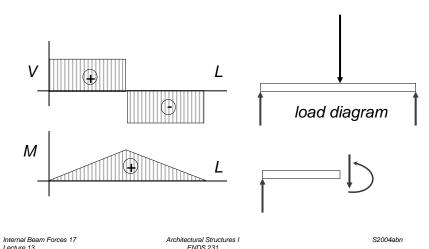
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# Bending Moment Sign Convention

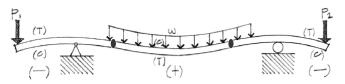


# Constructing V & M Diagrams

• along the beam length, plot V, plot M



#### Deflected Shape



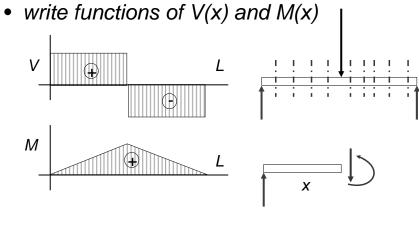
- positive bending moment
  - tension in bottom, compression in top
- negative bending moment
  - tension in top, compression in bottom
- zero bending moment
  - inflection point

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### Mathematical Method

cut sections with x as width

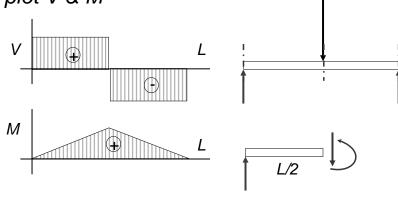


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## Method 1: Equilibrium

cut sections at important places





# Method 2: Semigraphical

by knowing

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– area under loading curve = change in V

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- area under shear curve = change in M
- concentrated forces cause "jump" in V
- concentrated moments cause "jump" in M

$$V_D - V_C = -\int_C^{X_D} w dx \qquad M_D - M_C = \int_C^{X_D} V dx$$

$$X_C$$

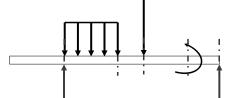
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#### Method 1: Equilibrium

- important places
  - supports
  - concentrated loads
  - start and end of distributed loads

- concentrated moments

- free ends
  - zero forces



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## Method 2

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#### relationships

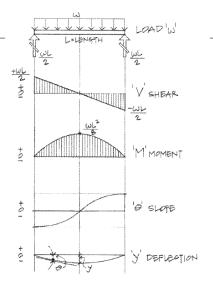


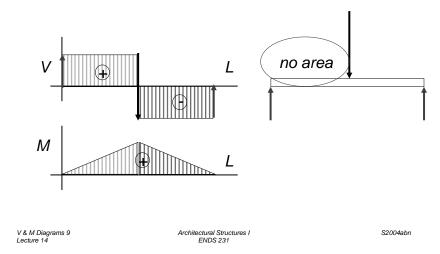
Figure 7.11 Relationship of load, shear, A moment, slope, and deflection diagrams.

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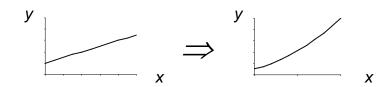
# Method 2: Semigraphical

•  $M_{max}$  occurs where V = 0 (calculus)



# Curve Relationships

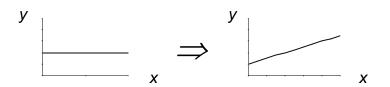
• line with slope, integrates to parabola



• ex: load to shear, shear to moment

#### Curve Relationships

- integration of functions
- line with 0 slope, integrates to sloped

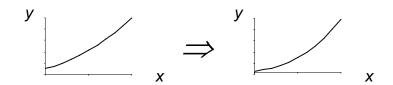


ex: load to shear, shear to moment

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# Curve Relationships

• parabola, integrates to 3<sup>rd</sup> order curve



• ex: load to shear, shear to moment

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#### Basic Procedure

Find reaction forces & moments
 Plot axes, underneath beam load diagram

V.

- 2. Starting at left
- 3. Shear is 0 at free ends
- 4. Shear jumps with concentrated load
- 5. Shear changes with area under load

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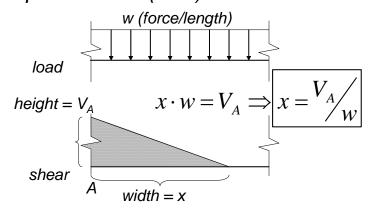
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*M*:

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# Triangle Geometry

• slope of V is w (-w:1)



# Parabolic Shapes

Basic Procedure

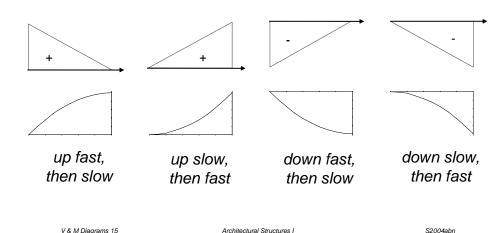
Starting at left

Moment is 0 at free ends

Moment jumps with moment

9. Moment changes with area under V

cases



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