Beam Structures and Internal Forces

Notation:

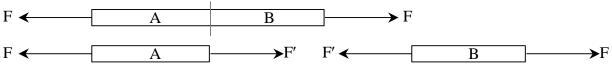
а	= algebraic quantity, as is b, c, d	R	= name for reaction force vector
A	= name for area	(T)	= shorthand for <i>tension</i>
b	= intercept of a straight line	V	= internal shear force
d	= calculus symbol for differentiation	V(x)	= internal shear force as a function of
(C)	= shorthand for <i>compression</i>		distance <i>x</i>
F	= name for force vectors, as is P, F', P'	W	= name for distributed load
	= internal axial force	W	= name for total force due to distributed
F_x	= force component in the x direction		load
F_{v}	= force component in the y direction	х	= horizontal distance
2	= free body diagram	у	= vertical distance
L	= beam span length	0	= symbol for order of curve
m	= slope of a straight line	1	= symbol for integration
M	= internal bending moment	Ā	= calculus symbol for small quantity
M(x)	= internal bending moment as a	Σ	= summation symbol
	function of distance <i>x</i>	-	

• BEAMS

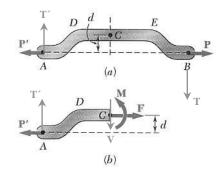
- Important type of structural members (floors, bridges, roofs)
- Usually long, straight and rectangular
- Have loads that are usually perpendicular applied at points along the length

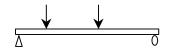
Internal Forces 2

- Internal forces are those that hold the parts of the member together for equilibrium
 - Truss members:



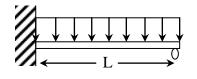
- For any member:
 - F = internal *axial force* (perpendicular to cut across section)
 - V = internal *shear force* (parallel to cut across section)
 - M = internal *bending moment*

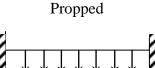




Support Conditions & Loading

- Most often loads are perpendicular to the beam and cause <u>only</u> internal shear forces and bending moments
- Knowing the internal forces and moments is *necessary* when designing beam size & shape to resist those loads
- Types of loads
 - Concentrated single load, single moment
 - Distributed loading spread over a distance, uniform or **non-uniform**.
- Types of supports
 - *Statically determinate*: simply supported, cantilever, overhang (number of unknowns < number of equilibrium equations)
 - *Statically indeterminate*: continuous, fixed-roller, fixed-fixed (number of unknowns < number of equilibrium equations)







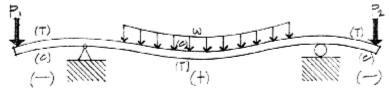
М

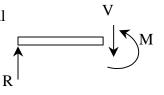
Sign Conventions for Internal Shear and Bending Moment (<u>different</u> from statics and truss members!)

When ΣF_y **excluding V** on the left hand side (LHS) section is <u>positive</u>, V will direct <u>down</u> and is considered <u>POSITIVE</u>.

When ΣM **excluding M** about the cut on the left hand side (LHS) section causes a smile which could hold water (curl upward), M will be <u>counter clockwise</u> (+) and is considered <u>POSITIVE.</u>

On the deflected shape of a beam, the point where the shape changes from smile up to frown is called the *inflection point*. The bending moment value at this point is **zero**.





Shear And Bending Moment Diagrams

The plot of shear and bending moment as they vary across a beam length are *extremely important design tools:* V(x) is plotted on the y axis of the shear diagram, M(x) is plotted on the y axis of the moment diagram.

The *load* diagram is essentially the free body diagram of the beam *with the actual loading (not the equivalent of distributed loads.)*

Maximum Shear and Bending – The maximum value, regardless of sign, is important for design.

Method 1: The Equilibrium Method

Isolate FDB sections at significant points along the beam and determine V and M at the cut section. The values for V and M can also be written in equation format as functions of the distance to the cut section.

Important Places for FBD cuts

- at supports
- at concentrated loads
- at start and end of distributed loads
- at concentrated moments

Method 2: The Semigraphical Method

Relationships exist between the loading and shear diagrams, and between the shear and bending diagrams.

Knowing the *area* of the loading gives the *change in shear* (V).

Knowing the *area* of the shear gives the *change in bending moment* (*M*).

Concentrated loads and moments cause a vertical jump in the diagram.

 $\frac{\Delta V}{\Delta x} = \frac{dV}{dx} = -w \qquad \text{(the negative shows it is down because we give w a positive value)}$ $V_D - V_C = -\int_{x_C}^{x_D} w dx = \text{the area under the load curve between C & D}$ $* <u>These shear formulas are NOT VALID at discontinuities like concentrated loads}</u>$

$$\frac{\Delta M}{\frac{\Delta x}{\lim 0}} = \frac{dM}{dx} = V$$

$$M_D - M_C = \int_{x_C}^{x_D} V dx = \text{the area under the shear curve between C & D}$$
* These moment formulas ARE VALID even with concentrated loads.

*These moment formulas are NOT VALID at discontinuities like applied moments.

The MAXIMUM BENDING MOMENT from a curve that is <u>continuous</u> can be found when the slope is zero $\left(\frac{dM}{dx} = 0\right)$, which is when the value of the shear is 0.

Basic Curve Relationships (from calculus) for y(x)

<u>Horizontal Line</u>: y = b (*constant*) and the area (change in shear) $= b \cdot x$, resulting in a:

Sloped Line: y = mx + b and the area (change in shear) $= \frac{\Delta y \cdot \Delta x}{2}$, resulting in a:

<u>Parabolic Curve</u>: $y = ax^2 + b$ and the area (change in shear) $= \frac{\Delta y \cdot \Delta x}{3}$, resulting in a:

<u>3rd Degree Curve</u>: $y = ax^3 + bx^2 + cx + d$

Free Software Site: http://www.rekenwonder.com/atlas.htm







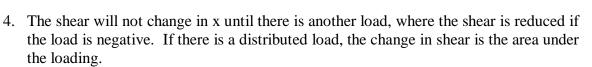


BASIC PROCEDURE:

1. Find all support forces.

V diagram:

- 2. At free ends and at simply supported ends, the shear will have a zero value.
- 3. At the left support, the shear will equal the reaction force.



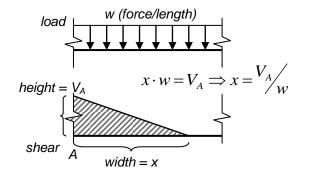
- 5. At the right support, the reaction is treated just like the loads of step 4.
- 6. At the free end, the shear should go to zero.

M diagram:

- 7. At free ends and at simply supported ends, the moment will have a zero value.
- 8. At the left support, the moment will equal the reaction moment (if there is one).
- 9. The moment will not change in x until there is another load or applied moment, where the moment is reduced if the applied moment is negative. If there is a value for shear on the V diagram, the change in moment is the area under the shear diagram.

For a triangle in the shear diagram, the width will equal the height \div *w*!

- 10. At the right support, the moment reaction is treated just like the moments of step 9.
- 11. At the free end, the moment should go to zero.

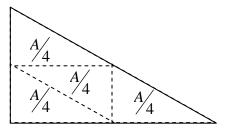


Parabolic Curve Shapes Based on Triangle Orientation

In order to tell if a parabola curves "up" or "down" from a triangular area in the preceding diagram, the orientation of the triangle is used as a reference.

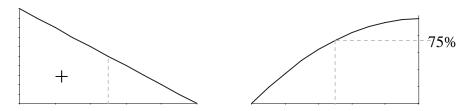
Geometry of Right Triangles

Similar triangles show that four triangles, each with ¹/₄ the area of the large triangle, fit within the large triangle. This means that ³/₄ of the area is on one side of the triangle, if a line is drawn though the middle of the base, and ¹/₄ of the area is on the other side.

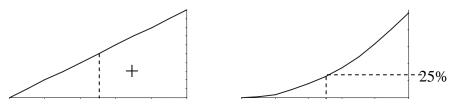


By how a triangle is oriented, we can determine the curve shape in the next diagram.

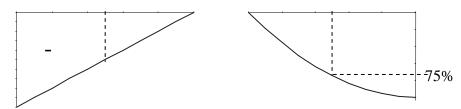
<u>CASE 1</u>: *Positive* triangle with fat side to the *left*.



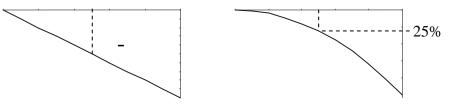
<u>CASE 2</u>: *Positive* triangle with fat side to the *right*.



CASE 3: Negative triangle with fat side to the *left*.



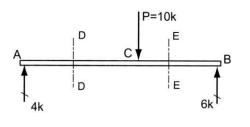
<u>CASE 4</u>: *Negative* triangle with fat side to the *right*.

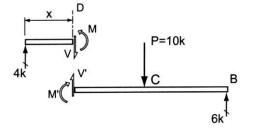


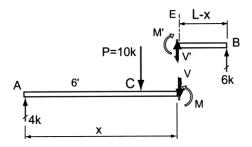
Example 1 (pg 273)

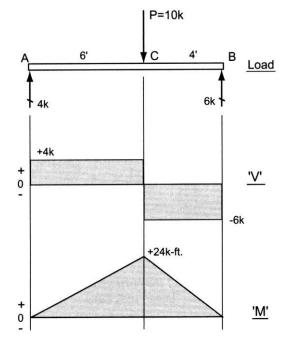
Example Problem 8.1 (Equilibrium Method)

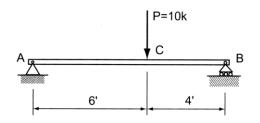
Draw the shear and moment diagram for a simply supported beam with a single concentrated load (Figure 8.8), using the equilibrium method. Verify the general equation from Beam Diagrams & Formulas.









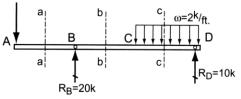


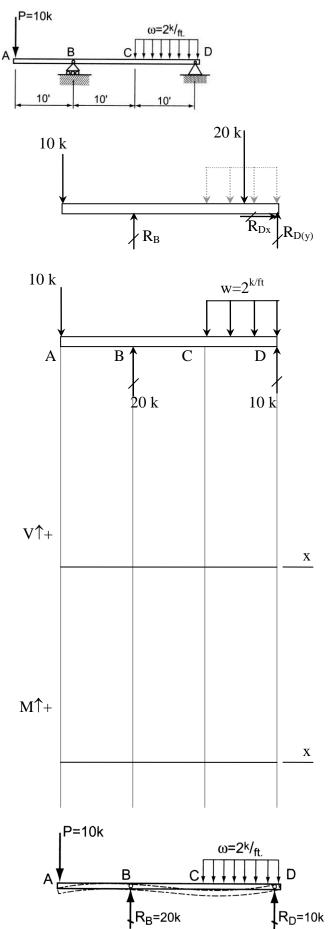
Example 2 (pg 275)

Example Problem 8.2(Equilibrium Method)

Draw V and M diagrams for an overhang beam (Figure 8.12) loaded as shown. Determine the critical $V_{\rm max}$ and $M_{\rm max}$ locations and magnitudes.

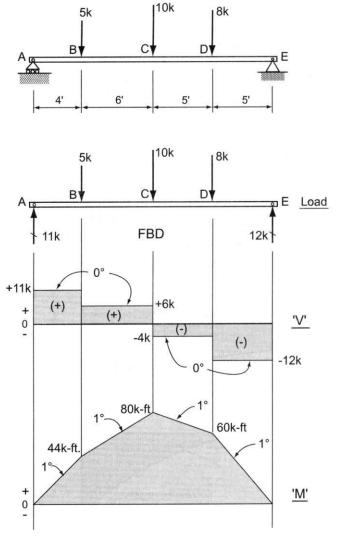
P=10k





Example 3 (pg 283) Example Problem 8.4

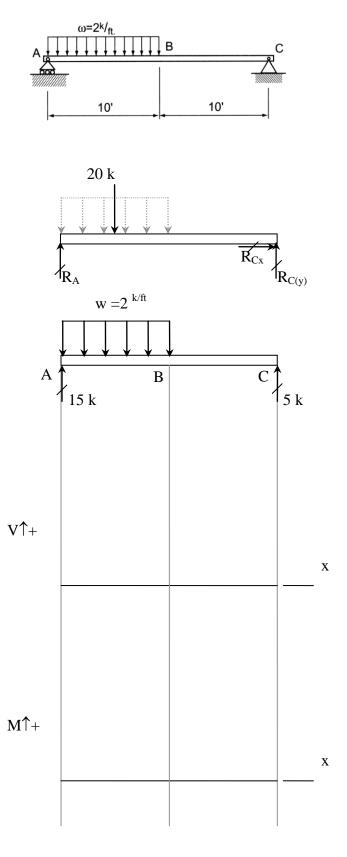
Construct the V and M diagrams for the girder that supports three concentrated loads as shown in Figure 8.28.



Example 4 (pg 285)

Example Problem 8.6 (Semi-Graphical Method)

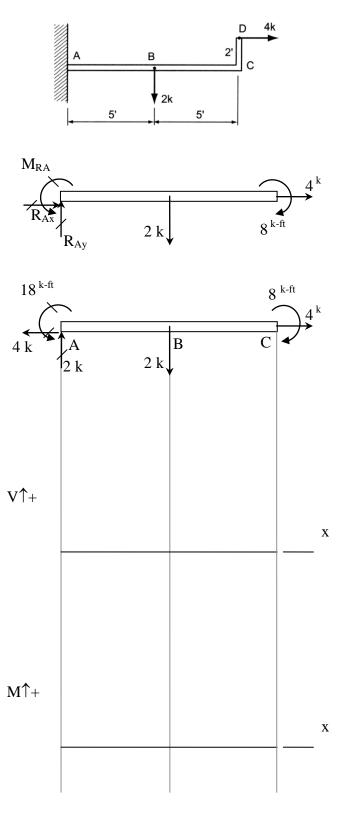
Construct V and M diagrams for the simply supported beam *ABC*, which is subjected to a partial uniform load (Figure 8.30).

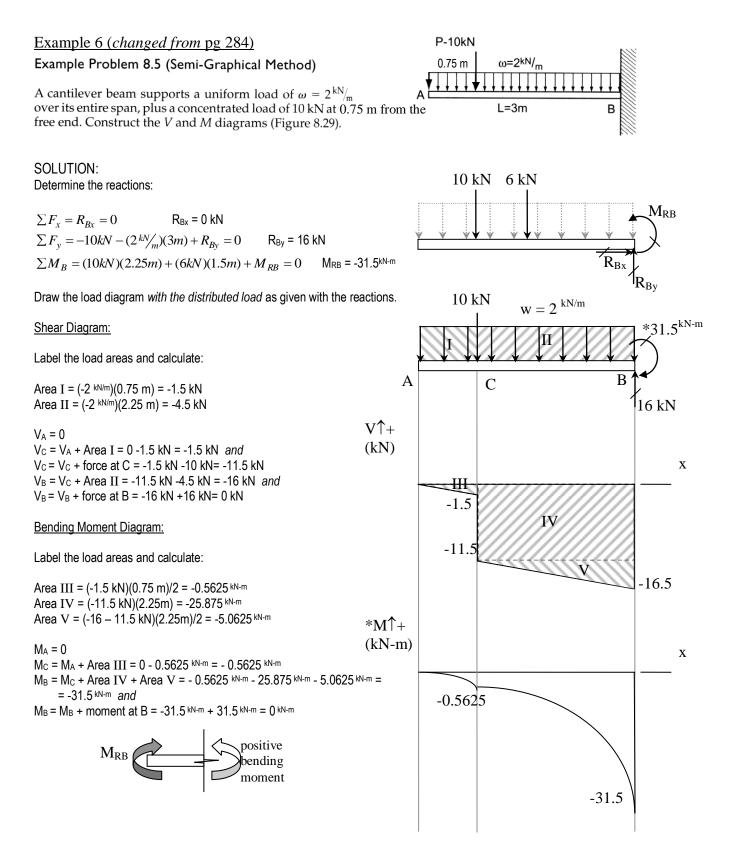


Example 5 (pg 286)

Example Problem 8.7 (Figure 8.31)

For a cantilever beam with an upturned end, draw the load, shear, and moment diagrams.





Example 7 (pg 287) Example Problem 8.9 (Figure 8.33)

A header beam spanning a large opening in an industrial building supports a triangular load as shown. Construct the V and M diagrams and label the peak values.

SOLUTION: Determine the reactions:

 $\Sigma F_x = R_{Bx} = 0 \qquad \text{R}_{\text{Bx}} = 0 \text{ kN}$ $\Sigma F_y = R_{Ay} - (300 \text{ N/m})(3m) \frac{1}{2} + -(300 \text{ N/m})(3m) \frac{1}{2} + R_{By} = 0$

or by load tracing $R_{Ay} \& R_{By} = (wL/2)/2 = (300 \text{ N/m})(6 \text{ m})/4 = 450 \text{ N}$

 $\sum M_A = -(450N)(\frac{2}{3} \times 3m) - (450N)(3 + \frac{1}{3} \times 3m) + R_{By}(6m) = 0$ R_{By} = 450 N

Draw the load diagram with the distributed load as given with the reactions.

Shear Diagram:

Label the load areas and calculate:

Area I = (-300 ^{N/m})(3 m)/2 = -450 N Area II = -300 ^{N/m})(3 m)/2 = -450 N

 $\begin{array}{l} V_A = 0 \; and \; V_A = V_A + \mbox{force at } A = 0 + 450 \; N = 450 \; N \\ V_C = V_A + \mbox{Area I} = 450 \; N - 450 \; N = 0 \; N \\ V_B = V_C + \mbox{Area II} = 0 \; N - 450 \; N = -450 \; N \; and \\ V_B = V_B + \mbox{force at } B = -450 \; N + 450 \; N = 0 \; N \end{array}$

Bending Moment Diagram:

Label the load areas and calculate:

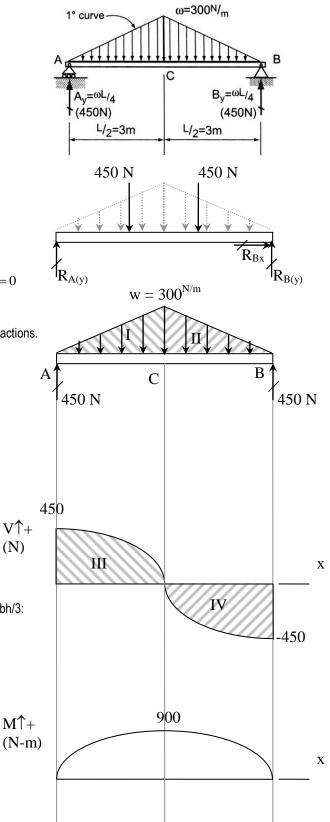
Areas III & IV happen to be parabolic segments with an area of 2bh/3: Area III = 2(3 m)(450 N)/3 = 900 N-mArea IV = -2(3 m)(450 N)/3 = -900 N-m

We can prove that the area is a parabolic segment by using the equilibrium method at C:

$$\sum M_{\text{sectioncut}} = M_C - (450N)(3m) + (450N)(\frac{1}{3} \times 3m) = 0$$

so M_c = 900 ^{N-m}
450 N

450 N



V